Atty Docket No. SRI1P030/US-4149-4 Application No.: 10/090,430

Information Disclosure Statement By Applicant Applicant: Heim, et al. Filing Date

Group

(Use Several Sheets if Necessary)

February 2, 2002

Unknown

Other Documents

		Other Documents				
Examiner						
Initial	No.	Author, Title, Date, Place (e.g. Journal) of Publication				
MB.	E1	Pelrine, R, R. Kornbluh, J. Joseph, and S. Chiba, "Electrostriction of Polymer Films for Microactuators," <i>Proc. IEEE Tenth Annual International Workshop on Micro Electro Mechanical Systems</i> , Nagoya, Japan, January 26-30, 1997, pp. 238-243.				
	E2	Pelrine, R., R. Kornbluh, and J. Eckerle. "Energy Efficient Electroactive Polymers and Electroactive Polymer Devices", U.S. Patent Application No. 09/779,373, filed February 7, 2001.				
	E3	Pelrine, R., and J. Joseph, FY 1992 Final Report on Artificial Muscle for Small Robots, ITAD-3393-FR-93-063, SRI International, Menlo Park, California, March 1993				
	E4	Pelrine, R., R. Kornbluh, and J. Joseph, FY 1999 Final Report on Artificial Muscle for Small Robots, ITAD-10162-FR-00-27, SRI International, Menlo Park, California, 2000				
	E5	Pelrine, R., R. Kornbluh, Q. Pei, and J. Joseph, "High Speed Electrically Actuated Elastomers with Over 100% Strain," <i>Science</i> , Vol. 287, No. 5454, pages 1-21, 2000				
	E6	Pelrine, R., Roy Kornbluh, Jose Joseph, Qibing Pei, Seiki Chiba "Recent Progress in Artificial Muscle Micro Actuators,", SRI International, Tokyo, 1999 MITI/NEEDOIMNIC, 1999				
	E7	Smela, E., O. Inganäs, Q. Pei, and I. Lundström, "Electrochemical Muscles: Micromachining Fingers and Corkscrews, "Advanced Materials, Vol.5, No. 9, pp.630-632, September 1993				
	E8	Wax, S. G. and R. R. Sands, "Electroactive Polymer Actuators and Devices," Proceedings of the SPIE International Symposium on Smart Structures and Materials: Electro-Active Polymer Actuators and Devices, March 1-2, 1999, Newport Beach, California, USA., pp. 2-10.				
	E9	Winters, J., "Muscle as an Actuator for Intelligent Robots", Robotics Research: Trans. Robotics International of SME, Scottsdale, AZ (August 21, 1986)				
Examiner	Mz	Date Considered 5-72-04				

Examiner: Initial citation considered. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

APR 2 8 2002

Form 449 (Modified)

Atty Docket No. SRI1P030/US-4149-4

Application No.: 10/090,430

Information Disclosure Statement By Applicant

Applicant: Heim, et al.

(Use Several Sheets if Necessary)

Filing Date
February 2, 2002

Group Unknown

Other Documents

		Other Documents					
Examiner							
Initial	No.	Author, Title, Date, Place (e.g. Journal) of Publication					
B	D1	Kornbluh, R. D and R. E. Pelrine., "Dexterous Multiarticulated Manipulator with Electrostrictive Polymer Artificial Muscle," ITAD-7247-QR-96-175, SRI Project Number 7247, Prepared for: Office of Naval Research, November 1996					
ļ -	D2	Lang, J. M. Schlect, and R. Howe, "Electric Micromotors: Electromechanical					
		Characteristics," Proc. IEEE Micro Robots and Teleoperators Workshop, Hyannis, Massachusetts (November 9-11, 1987).					
	D3	awless, W. and R. Arenz, "Miniature Solid-state Gas Compressor," Rev. Scinstrum., 58(8), pp.1487-1493, August 1987					
	D4	Iguyen, T., J. A. Willett and Kornbluh, R., "Robotic systems," in ONR Ocean, Atmosphere, and Space Fiscal Year 1998 Annual Reports (Dec. 1998)					
	D5	Olsson, A., G. Stemme, and E. Stemme, "The First Valve-less Diffuser Gas Pump," Tenth Annual International Workshop on Micro Electromechanical Systems, Nagoya, Japan, <i>IEEE Proceedings</i> (January 26-30, 1997), pp.108-113.					
	D6	R. Pelrine and Kornbluh, R., and. 1995. "Dexterous Multiarticulated Manipulator with Electrostrictive Polymer Artificial Muscle Actuator," EMU 95-023, SRI International, Menlo Park, California, April 28, 1995.					
	D7	Pelrine, R. and Kornbluh, "Electroactive Polymer Devices", U.S. Patent Application No. 09/619,846, filed July 20, 2000, 67 pages					
	D8	Pelrine et al., "Electroactive Polymer Generators", U.S. Patent Application No. 09/619,848, filed July 20, 2000, 69 pages					
	D9	Pelrine, R., R. Kornbluh, and J. Joseph, "Electrostriction of Polymer Dielectrics with Compliant Electrodes as a Means of Actuation," Sensors and Actuators A: Physical, Vol. 64, 1998, pp.77-85.					
	D10	Pelrine, R., R. Kornbluh and J. Eckerle, "Monolithic Electroactive Polymers", U.S. Patent Application No. 09/779,203, filed February 7, 2001, 47 pages					
	1						
Examiner	Mar	Date Considered					
<u></u>		NY EXAMINER Solution conformance and					

Examiner: Initial citation considered. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.



Form 10140 (Wified)

Atty Docket No. SRI1P030/US-4149-4 Application No.: 10/090,430

Information Disclosure Statement By Applicant Applicant:
Heim, et al.
Filing Date

Group

(Use Several Sheets if Necessary)

February 2, 2002

Unknown

Other Documents

		Other Documents					
Examiner							
Initial	No.	Author, Title, Date, Place (e.g. Journal) of Publication					
	C1	De Rossi, D., and P. Chiarelli. 1994. "Biomimetic Macromolecular					
Ola.		Actuators," Macro-Ion Characterization, American Chemical Society					
MD	.	Symposium Series, Vol. 548, Ch. 40, pp. 517-530.					
	C2	Dowling, K., Beyond Faraday-Non Traditional Actuation, available on the					
		World Wide Web at http://www.frc.ri.cmu.edu/~nivek/OTH/beyond-					
[faraday/beyondfaraday.html, 9 pages, 1994					
	C3	Flynn, Anita M., L.S. Tavrow, S.F. Bart, R.A. Brooks, D.J. Ehrlich, K.R.					
	-	Udayakumar, and L.E. Cross. 1992. "Piezoelectric Micromotors for					
	1	Microrobots," IEEE Journal of Microelectromechanical Systems, Vol.1, No.1,					
		pp. 44-51 (March 1992); also published as MIT Al Laboratory Memo 1269,					
1		Massachusetts Institute of Technology (February 1991).					
	C4	Hirose, S., Biologically Inspired Robots: Snake-like Locomotors and					
	-	Manipulators, "Development of the ACM as a Manipulator", Oxford					
	Ì	University Press, New York, 1993, pp.170-172.					
	C5	Jacobsen, S., Price, R., Wood, J, Rytting, T., and Rafaelof, M., "A Design					
\	1	Overview of an Eccentric-Motion Electrostatic Microactuator (the Wobble					
		Motor)", Sensors and Actuators, 20 (1989) pages 1-16					
	C6	Kornbluh, R., G. Andeen, and J. Eckerle, "Artificial Muscle: The Next					
		Generation of Robotic Actuators," presented at the Fourth World Conference					
		on Robotics Research, SME Paper M591-331, Pittsburgh, PA, September 17-					
1 \		19, 1991.					
	C7	Kornbluh, R., Pelrine, R., Eckerie, J., Joseph, J., "Electrostrictive Polymer					
]		Artificial Muscle Actuators", IEEE International Conference on Robotics and					
1 1		Automation, Leuven, Belgium, 1998					
	C8	Ford, V. and J. Kievet, "Technical Support Package on Traveling-Wave					
Rotary Actuators" NASA Tech Brief Vol. 21, No. 10, Item #145, from							
		New Technology Report NPO-19261, October 1997					
Examiner	MA	/ Date Considered					
1	1//2	5-70-04					
<u> </u>	NAKA	EVAMINER : 1 D 1: 11 d incident in conformance and					

Examiner Rimanal Examiner Considered. Draw line through citation if not in conformance and not considered. Unformation with next communication to applicant.



F rm 1420(Modified)

Atty Docket No. SRI1P030/US-4149-4

Application No.: 10/090,430

Inf rmation Disclosure Statement By Applicant Applicant: Heim, et al.

Group

(Use Several Sheets if Necessary)

Filing Date
February 2, 2002

Unknown

U.S. Patent Documents

T	1		7	T Documents		Sub-	Filing
Examiner Initial	No.	Patent No.	Date	Patentee	Class	class	Date
1110	A1	5,977,685	11/02/99	Kurita, et al.			06/03/96
1112	A2	6,060,811	05/09/00	Fox, et al.	~		07/25/97
	A3	6,084,321	07/04/00	Hunter, et al.	7		08/07/98
	A4	6,184,608	02/06/01	Cabuz, et al.	1		12/29/98
	A5	6,184,609	02/06/01	Johansson, et al.	6-		03/26/97
	A6	6,249,076	06/19/01	Madden, et al.	_		04/14/99
	A7	4,885,783	12/05/89	Whitehead, et al.	-		04/10/87
	A8	4,236,416	12/02/80	Barcita			9/28/78
	A9	4,240,535	12/23/80	Pierce et al.	-		12/23/80
- //	A10		10/14/80	Tam	-		9/14/78

Other Documents

		0.20. 200						
Examiner								
Initial	No.	Author, Title, Date, Place (e.	Author, Title, Date, Place (e.g. Journal) of Publication					
	B 1		orldwide Electroactive Polymers, EAP (Artificial					
M		Muscles) Newsletter, Vol. 3,	No.1, June 2001					
	B2	Baughman, R.H., L.W. Shac	klette, and R.L. Elsenbaumer, E. Plichta, and C.					
_	1		ical actuators based on conducting polymers", in					
NR.	1	Molecular Electronics, Mate	rials and Methods, P.I. Lazarev (ed.), Kluwer					
\ ///\}		Academic Publishers, pp. 26	Academic Publishers, pp. 267-289 (1991)					
000	B3		ificial Muscle based on Contractile Polymers,"					
/W		MIT Artificial Intelligence I	aboratory, A.I. Memo No. 1330, Nov. 1991.					
1	B4	Caldwell, D., G. Medrano-C	erda, and M. Goodwin, "Characteristics and					
	1		atic Muscle Actuators for a Robotic Elbow," Proc.					
200	1	IEEE Int. Conference on Robotics and Automation, San Diego, California (8-						
		13 May 1994).						
M	ARK U	BUDD						
ExaminerI	ExaminaDIMARV EXAMINER		Date Considered					
, , , , , , , , , , , , , , , , , , ,	DT//N	ि २०५	5-20-04					
	5.4 L 3.44 B	1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1					

Examiner: Initial citation considered. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.



GOPY OF PAPERS ORIGINALLY FILED

F rm 1449 (Modified) ATENT & TRADER

Information Disclosure Statement By Applicant

Atty Docket No. SRI1P030/US-4149-4 Application No.: 10/090,430

Applicant:

Pelrine et al.

(Use Several Sheets if Necessary)

Filing Date February 28, 2002

Group 2834

U.S. Patent Documents

Examiner Initial	No.	Patent No.	Date	Patentee	Class	Sub- class	Filing Date
	A						
	В					 	-
	С						
	D						

Foreign Patent or Published Foreign Patent Application

Examiner		Document	Publication			Sub-	Tran	slation
Initial	No.	No.	Date	Patent Office	Class	class	Yes	No
	J							1
	K					<u> </u>	†	
	L					 	+	

Other Documents

Examiner	1							
Initial	No.	Author, Title, Date, Place (e.g. Journal) of Publication						
M	0	Roy D. Kornbluh, "Robotic Systems, Ocean Engineering and Marine Sy 2000 Program, January 2001, Office of Naval Research Public Release, 32100-1						
MR,	P	Roy D. Kombluh, "Robotic Systems, Ocean Engineering and Marine Systems, 1999 Program, February 2000, Office of Naval Research Public Release, ONR 32100-2						
Mb	Q	Roy D. Kornbluh, "Robotic Systems, Ocean Engineering and Marine Systems, 1998 Program, February 1999 Office of Naval Research Public Release, ONR 32199-4						
m	R	Roy D. Kornbluh, Robotic Systems, Ocean Engineering and Marine Systems 1997 Program, December 1997, Office of Naval Research Public Release, ONR 32198-2						
Examiner of	HATTON.							

Examined. BUDDY

Date Considered 5-20-04

Examination is considered. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

m 1449 (Modified)

Information Discl sure **Statement By Applicant** Atty Docket No.

Application No.: 10/090,430

SRI1P030 Applicant: Heim, et al..

Filing Date

Group

(Use Several Sheets if Necessary)

February 28, 2002

2834

U.S. Patent Documents

			0121 2 22	<u> </u>			
Examiner						Sub-	Filing
Initial	No.	Patent No.	Date	Patentee	Class	class	Date
AP	A1	5,761,782	06/9/98	Sager			02/18/97
1,	A2	6,194,815	02/27/01	Carroll			02/19/99
V	A3	6,069,420	05/30/00	Mizzi, et al.			04/21/99

Foreign Patent or Published Foreign Patent Application

Examiner		Document	Publication	Country or		Sub-	Trans	slation
Initial	No.	No.	Date	Patent Office	Class	class	Yes	No
N	B1	WO 01/06579	01/25/01	WIPO			X	
Hs	B2	WO 01/58973	08/16/01	WIPO			X	
	<u> </u>					<u> </u>		
								ļ
	i	ł				1	1	

Other Documents

Examiner Initial	No.	Author, Title, Date, Pla	ce (e.g. Journal) of Publication
	,		
Examiner	· · · · · (MARY EXAMINER	Date Considered 5-70-04

Examiner: Initial chapped considered. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.